Database:

## Refine Search

#### Search Results -

Term	Documents
(2 AND 1).PGPB.	1}
(L1 AND L2 ).PGPB.	1,

US Pre-Grant Publication Full-Text Database
US Patents Full-Text Database
US OCR Full-Text Database
EPO Abstracts Database
JPO Abstracts Database

Derwent World Patents Index IBM Technical Disclosure Bulletins

Search:

Refine Search

Recall Text

Clear

Interrupt

### **Search History**

DATE: Thursday, July 05, 2007 Purge Queries Printable Copy Create Case

**Set Name Query Hit Count Set Name** side by side result set DB=PGPB; THES=ASSIGNEE; PLUR=YES; OP=ADJ L3 11 and L2 1 <u>L3</u> L2 (function with accelerations with directions with motion).clm. 2 <u>L2</u> (sensor with acceleration with acquisition with direction).clm. L1 <u>L1</u>

**END OF SEARCH HISTORY** 

# Refine Search

### Search Results -

Term	Documents
(8 AND 6).PGPB,USPT,EPAB,JPAB,DWPI,TDBD.	0
(L6 AND L8 ).PGPB,USPT,EPAB,JPAB,DWPI,TDBD.	0

Database:	US OCR Full-Text Database EPO Abstracts Database JPO Abstracts Database	
	Derwent World Patents Index IBM Technical Disclosure Bulletins	
Search:	L14	Refine Search
	Recall Text Clear	Interrupt

## **Search History**

DATE: Thursday, July 05, 2007 Purge Queries Printable Copy Create Case

US Pre-Grant Publication Full-Text Database

Set Name side by side	Query	Hit Count	Set Name result set
•	,USPT,EPAB,JPAB,DWPI,TDBD; THES=ASSIGNEE; PLUR=Y	ES; OP=ADJ	result see
<u>L14</u>	l6 and l8	0	<u>L14</u>
<u>L13</u>	l6 and l11	0	<u>L13</u>
<u>L12</u>	5229943.pn.	2	<u>L12</u>
DB = USPT	: THES=ASSIGNEE; PLUR=YES; OP=ADJ		
<u>L11</u>	(5229943   5790404   5626359)![PN]	3	<u>L11</u>
<u>L10</u>	("6711485")[PN]	. 1	<u>L10</u>
DB=PGPB	,USPT,EPAB,JPAB,DWPI,TDBD; THES=ASSIGNEE; PLUR=Y	YES; OP=ADJ	
<u>L9</u>	7039513.pn.	2	<u>L9</u>
DB = USPT	: THES=ASSIGNEE; PLUR=YES; OP=ADJ		
<u>L8</u>	("6711485")[URPN]	2	<u>L8</u>
DB=PGPB	,USPT,EPAB,JPAB,DWPI,TDBD; THES=ASSIGNEE; PLUR=Y	YES; OP=ADJ	
<u>L7</u>	11 and L6	. 1	<u>L7</u>
<u>L6</u>	l4 and L5	13	<u>L6</u>

<u>L5</u>	classif\$ near2 impact	543	<u>L5</u>
<u>L4</u>	12 and L3	600	<u>L4</u>
<u>L3</u>	acceleration near2 signal	19750	<u>L3</u>
<u>L2</u>	detect\$ near2 impact	8659	<u>L2</u>
<u>L1</u>	sensor near2 acceleration near2 acquisition	15	<u>L1</u>

## END OF SEARCH HISTORY